		Government (College of Engi	neering, Karad	l	
			8. Tech (Electri			
			701: Electrical			
Teaching	Schen			Examination Sche	1	
Lectures		03 Hrs./week		CT 1	15	
Tutorials		02 Hrs./week		CT 2	15	
Total Cre	dits	05		ТА	10	
				ESE	60	
				Duration of ESE	2Hrs.30	Min.
Course O	bjectiv	ves	· · · · · ·			
1.			e of Electric Drive s	ystems and their role	in various	
2		lications.	1 1		. 11 1	
2.		lerstand the basic priverters.	inciples of control as	spects in drives using	controlled	
3.			pts of operation and	modern control aspec	ets of ac and	l dc
	mot					
4.			ic drive for various a	applications in indust		
		Course Contents				ours
				ives, Parts of Electri	cal drive,	06
		oice of Electric drive				
Unit I				ental torque equation		
				n of load torques, ste	eady state	
			d equalization in driv	operation like Stea	dv state	06
			ion, Drive classificat	-	idy state,	vu
TT •/ TT			-	t control, torque cont	rol, speed	
Unit II		-		motor drives, speed	· 1	
	curr	ent sensing, Classe	s of motor duty, crite	ria for selection of m	otor	
				eristics of DC motors		08
				e converter fed drive	-	
	-		-	nverter drives, Full	converter	
		es, Dual converter		Three mhases half was	to driver	
		-		Three phase half way dual converter drives		
T • 4 T T				of rheostatic and reg		
Unit III			-	and four quadrant		
		verter fed drives.	unea control, the	una rour quaarant	2020	
	Intro	oduction to closed	loop control of DC	drives, and brushle	ess motor	
	driv		-			
Unit IV	Ind	uction Motor Driv	es: Review of starting	g, braking and speed	control of	06
- • •				control, Rotor voltag		
	freq	uency control, Vol	tage and frequency	control (v/f control)	, Current	
				notors, Principle of S		
			-	adrant operation of	induction	
			/oltage Source Inver			
				c slip power recovery	y control-	
	Stat	ic Scherblus drive a	nd Static Kramer dri	ve.		

Unit V	Synchronous Motor Drives: Review of starting, pull in and braking of Synchronous motor, Static variable frequency control for Synchronous motors, Load commutated inverter fed Synchronous motor drive, Introduction to closed loop control of Load commutated inverter fed Synchronous motor drive.	06
Unit VI	 Drives for Specific Applications: (i) Textile Mill: various stages and drive requirements, control of ac motors for controlling torque. (ii) Steel Rolling Mill: reversing and continuous hot and cold rolling mills, Drive requirements, motors for mill drive. (iii) Cement Mill: Stages in cement production, requirements of mill motors, Kiln drives, crusher drives, fan/blower drives, compressor drive. (iv) Sugar Mill: Requirements for various drive motors, selection of motors for various processes. (v) Drives in other applications: Chemical/Petrochemical Industries, Machine tool applications, miscellaneous applications like automobile control for vehicle, hybrid drives, applications of permanent magnet machines etc. Introduction to IS standard (like IS325) 	06
Tutorial	machines etc. Introduction to 15 standard (Inte 15526)	
	Two tutorials based on each Unit.	
Course O	utcomes	
After Con	npletion of the course student will be able to	
1.	apply knowledge of mathematics to solve numerical based on dynamics of c to study various parameters for effective control of drives and converters to output power.	
2.	describe the drive characteristics used in industry and of power semiconduct devices and identify suitable controller for a given application.	tor
3.	enjoy overall ability to use different techniques, and modern engineering too necessary for electrical drives in practice.	ols
Text Bool		
1.	"Fundamentals of Electrical Drives", G. K. Dubey, Narosa Publishing house	e
2.	"A first course in Electrical Drives", S. K. Pillai, New Age International Publishers, 3 rd edition.	
Reference	29S	
1.	"Electrical Drives and Control", Vedam Subramanyam, TMH Publications	
2.	"Electric Drives", N. K. De, P. K. Sen, Prentice Hall of India	
3.	"Electrical Motor Drives: Modeling, Analysis and Control", R. Krishnan,	
	Prentice Hall (I) Pvt. Ltd.	
Useful Li	nks	
1.	http://nptel.ac.in/courses/108102046/	
2.	http://nptel.ac.in/courses/108108077/	
3.	http://nptel.ac.in/courses/108104011/	

	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PS O1	PS O2
CO1														\checkmark
CO2									\checkmark	\checkmark				\checkmark
CO3														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

		Governme	nt College of En	gineering, Kara	d			
		Final Yea	r B. Tech (Elect	trical) Sem. VII				
			2: Switchgear a	/				
Teachi	ng Schen		8	Examination Sche	me			
Lecture	<u> </u>	3 Hrs./week		CT1	15			
Tutoria		1		CT2	15			
Total C	Credits	4		TA	10			
				ESE D (CESE	<u>60</u>	•		
Course	Objectiv	205		Duration of ESE	2Hrs.30 M	in.		
1.	Objectiv		principles of various C	Tircuit Breakers				
2.			principles of protective					
3.				rious protections in po	wer systems			
5.		Course Contents		nous protections in po	-	ours		
Unit I			ent. Basic Elements	of Circuit Breaking		<u>0115</u> 06		
O III I		-		striking voltage, Volta		00		
		-		Breaking, Circuit Break	•			
Unit II	Circuit Breakers: Classification, Oil Circuit Breakers, Air Circuit Breakers, SF6 06							
0 1110 11	Circuit Breakers, Vacuum Circuit Breakers, DC Circuit Breakers							
Unit III								
	Transfo	rmers and their us	e in protection					
				, Static Relays, Numer				
Unit IV				abnormal operating		06		
		-	, Differential Protectio	on, Restricted Earth fau	Ilt protection,			
Unit V		rrent protection,	Various faults and	abnormal operating	Conditions	08		
Unit v				ricted earth fault and in		00		
			nsformer Unit protecti					
Unit VI		•		nt protection, Distance	protection.	06		
	Protect	ion against Ov	ver voltage: Causes	of overvoltage, p	rotection of			
				inst over voltage saf	ety features,			
C		easons and mainte	enance					
	Outcom		working minsinlag of	Variana Circuit Drast-	280			
1.			<u> </u>	various Circuit Breake				
2.				for different protectio	n scheines			
3.		it will understand	various protections in	power systems.				
Text Bo		E Dao Switchas	r Drotaction and name	provotoma Vhanna Du	bligation 2000			
1. Referei		5. Kao, Switchgea	i, Frotection and powe	er systems, Khanna Pu	oncation,2008			
1.		Ram, D Vishvakarn	a;Power System Protect	tion and Switchgear, Tata	a McGrawhill.2/e	2		
2.				alja; Protection and swit				
	Press	,		~ ^	<u> </u>			
Useful								
1.		ocw.mit.edu						
2.	WWW.1	nptel.iitm.ac.in						

	PO	PO	PO	PO	РО	PO	PO	PO	PO	PO	PO	PO	PSO	PSO
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1														
CO2														
CO3										\checkmark			\checkmark	

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

	Government College	of Engineering, Karad	
		(Electrical) Sem. VII	
		crocontrollers	
Teaching S		Examination Sche	
Lectures	3 Hrs./week	CT1	15
Total Cred	lits 3	CT2	15
			10
		ESE	60
		Duration of ESE	2Hrs.30 Min.
Course Ob			
1.	Provide an overview of di controller.	fference between microprocessor	and micro
2.	Give an understanding abou	t the concepts and basic architect	ure of 8051.
3.	Study the architecture and a	ddressing modes of 8051.	
4.		embly language programs of 805	
5.	Help understand the import interfacing to 8051.	ance of different peripheral devi	ices & their
6.	Impart knowledge of diffe	erent types of external interface x, Switches & Seven segment disp	-
		, switches & seven segment dis	Jidy.
Course Co	ntent		Hours
		ocontrollers: Evolution fro	
		ntrollers. Block diagram description	
	-	struction cycle, Timing Diagra	
TT *4 T		xamples, memory organization	
Unit I		ogramming. Introduction to vario RISC and CISC processor	
	-	ed processors, Overview of the 805	
		, Pin description of the 8051,RA	
	and ROM Organization in 80		7
		Programming: 8051 Addressin	
		ster addressing modes, Accessin	
	-	ssing modes, Bit addresses for I/	-
	and RAM, Extra 128-byte of	on-chip RAM in 8052.Concept	of
	Instruction cycle, Machine	e cycle. Types of Instruction	ns
Unit II	,Introduction to 8051 assemb	oly programming, Assembling an	nd
		e program counter and ROM spa	
	• -	nd directives, 8051 flag bits and the	
		banks and stack. Jump, Loop, Ai	
		ogramming. Arithmetic and Log	
	Instructions and Programs.		7
		ata types and time delay in 8051	
		, Logic operations in8051 C, Da	
TT •/ TTT		C, Accessing code ROM space	
Unit III		using 8051 C. 8051 Hardwa	
	Connection and Intel Hex File	2	4

Unit IV	8051 Timer Programming in Assembly and C: Programming	
	8051 timers, counter programming, Programming timers 0 and 1	
	in 8051 C as well as in assembly.	3
	8051 Serial Port Programming in Assembly and C: Basics of	
Unit V	serial communication, 8051 connection to RS232, 8051 serial port	
	programming in Assembly, Programming the second serial port,	
	Serial port programming in C.	3
	Interrupts Programming in Assembly and C: 8051 interrupts	
Unit VI	programming, Timer interrupts, Programming external hardware	
	interrupts, Programming the serial communication interrupt,	
	Interrupt priority in the 8051/52, Interrupt programming in C.	4
	Interfacings of 8051: Details of LCD interfacing, Keyboard	
	interfacing. Parallel and serial ADC, DAC interfacing, Sensor	
	interfacing and signal conditioning. Semiconductor memory,	
Unit VII	Memory address decoding, 8031/51 interfacing with external	
	ROM, Flash RAM, 8051 data memory space, Accessing external	
	data memory in 8051C. RTC Interfacing and	
	Programming. Motor Control: Relay, PWM, DC and Stepper	7
	Motors PWM. ARDUINO	
	Microcontrollers in Power systems: Phase detection,	
Unit VIII	Measurement of Voltage, current and Power. PWM generation for	
	converters, Applications in protection and switchgear and its	-
C O	controller. CE marking VDE marking CSA, UL marking	7
	tcome (CO):	
	pletion of the course student will be able to	
1.	Explain the difference between microprocessor and microcontrol	ler
2.	Explain different addressing modes of 8051	
3.	Explain the working of various peripherals and their interfacing	
4.	Write assembly as well as c programs for 8051	
5.	Design system based on 8051 for electrical engineering application	ons
Text Books		17.1
1.	Muhammad Ali Mazidi, Janice Gillispie Mazidi and Rolin M	
	"The 8051 Microcontroller and Embedded Systems Using Asser C", Second Edition, Pearson Education.	noly and
2.		mbaddad
۷.	K. J. Ayala, D. V. Gadre, "The 8051 Microcontroller & En Systems using Assembly and C", Cengage Learning, India Edition	
Reference l		/11.
1.	Satish Shah, "8051 Microcontrollers: MCS51 family and its v	ariants"
1.	Oxford University Press.	uriants ,
2.		ructions,
2.	Programming and Interfacing", Pearson Education.	i detions,
3.	K Uma Rao, Andhe Pallavi, "The 8051 Microcontrollers: Arch	itecture
5.	Programming and Applications", Pearson Education.	
Useful Linl		
1.	http://nptel.ac.in/courses/Webcourse-contents/IIT-	
	KANPUR/microcontrollers/ micro/ui/TOC.htm	
2.	http://freevideolectures.com/Course/3018/Microprocessors-and-	
	Microcontrollers	

	PO	PSO	PSO											
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1														
CO2														
CO3														
CO4														
CO5														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	5	5	2	10
Understand	5	5	2	20
Apply	5	5	2	10
Analyze	-	-	2	10
Evaluate	-	-	2	10
Create	-	-	-	-
Total	15	15	10	60

	G	overnment	t College of	f Enginee	ring, Ka	nrad			
		Final Year	· B. Tech (l	Electrical) Sem. V	II			
			05: Electri						
Laborato	ry Scl	neme			Examinati	on Scheme			
Practical		2 Hrs./week			CA	50			
Total Cre	dits	1			ESE	50*			
					Total	100			
Course O	bjecti	ves							
1.		inderstand imposion in selection			drive torque	e characteristics, its			
2.	1	elect and development development electrical drives i	1 /	their control	techniques	essential for control			
3.		imulate the descharacteristics of				drives and analyze			
Course Co	onten	ts							
Experimer	nt1	Control of DC	C motor using s	ingle phase c	onverters.				
Experimer	nt 2	Control of DC	C motor using t	hree phase co	onverters.				
Experimen	nt 3	Control of DC	C motor using I	DC-DC conve	erters.				
Experimen	nt 4	Control of DC	C motor using d	lual converter	S.				
Experimer	nt 5	V/f control of	³ -ph induction motor using 3-ph inverters.						
Experimer		Performance inverters.	characteristics	s of 3-ph induction motor fed from 3-ph					
Experimer	nt 7	Study of contr	rol techniques of	of brushless r	notor fed fr	rom converters.			
Experimer	nt 8	Simulations s	tudy of scalar c	control of 3-p	h induction	motor.			
Experimer	nt 9	Simulation stu induction mot	-	ontrol Direct	Torque Co	ntrol (DTC) of 3-ph			
Experimer	nt 10	Simulation stu induction mot		ontrol Field (Driented Co	ontrol (FoC) of 3-ph			
Submiss	ion:	I							
ESF	2	Minimum 8 e journal.	xperiments to b	be performed	simulated	and evaluated in			
Course O									
	pletir	ng this course s							
1.			electrical drive						
2.				rol technique	es applicab	le for AC and DC			
3.		-		te advanced	control sch	nemes for electrical			
		drives.							

	PO	PSO	PSO											
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1														
CO2														
CO3														

Skill Level (as per CAS Sheet)	Exp 1	Exp 2	Exp 3	Exp 4	Exp 5	Exp 6	Exp 7	Exp 8	Avg.
Task I	15	15	15	15	15	15	15	15	
Task II	05	05	05	05	05	05	05	05	
Task III	05	05	05	05	05	05	05	05	
CA									

(Government College	of Engineering, Karad	
	Final Year B. Tech	(Electrical) Sem. VII	
	EE 1706: Switchge	ar and Protection Lab	
Laboratory Sc	8	Examination Scheme	
Practical	2 Hrs./week	СА	50
Total Credits	1	ESE	25
		Total	75
Course Object			
After completio	n of the course student will		
1.		d working of different Relays.	
2.	understand operation and	d working of various protection schemes.	
3.	understand construction	of different Circuit breakers.	
Course Conten			
Experiment 1	Drawing Sheet showing Line Diagram of Substa	construction of Circuit Breakers. Single tion.	
Experiment 2	Drawing Sheet showi	ng Protections of Transformer and	
1	Generator.		
Experiment 3	Study of Construction and	nd working of Induction Disc Relays.	
Experiment 4	IDMT relay characterist		
Experiment 5	Operation and character	istics of over voltage Relay.	
Experiment 6	Operation and character	istics of under voltage Relay.	
Experiment 7	Operation and character	istics of over current Relay.	
Experiment 8	Operation of Buchholz I	Relay.	
Experiment 9	Operation and working	of feeder protection.	
Experiment 10	Operation and working of	of Differential protection of Transformer	
Experiment11	Operation and working	of Differential protection of Alternator	
Submission	1		
	of Experiments 8		
Course Outcor			
1.		handle different types of Relays.	
2.		working of Generator, Feeder and	
	Transformer protection s		
3.	Students will develop ele	ectrical drawing skill.	

	PO	PO	PO	PO	PS	PS								
	1	2	3	4	5	6	7	8	9	10	11	12	01	O2
CO1														
CO2														
CO3									\checkmark					

Knowledge Level	ТА	ESE
Remember	2	12
Understand	2	12
Apply	2	12
Analyze	2	12
Evaluate	2	12
Total	25	60

G	overnment	College of I	Engineering, I	Karad									
]	Final Year	B. Tech. (El	ectrical) Sem	. VII									
		· · ·	ntroller Lab										
Laboratory Sch			Examination	1 Scheme									
Practical	2 Hrs./week		CA	50									
Total Credits	1		ESE	25*									
			Total	75									
Course Objectiv													
1.			anguage programm	•									
<u>2.</u> 3.			ipheral devices and										
3.			ning and virtual	simulation of system									
	designed in F												
4.			of various inbuilt	modules like Timers,									
<u> </u>	counters, Inte	errupts, etc.											
Course Content													
Experiment 1		rogram to add t		stored in registers or									
		•		s stored in registers or									
			-	s stored in registers of									
		internal/External memory locations.c) Write a program to multiply two 16-bit numbers.											
Experiment 2				ed in internal/external									
Emperanen 2	memory loca	U											
	-	b) Write a program to transfer block of data from internal memory											
	locations to external memory locations.												
				cending or descending									
	order.	-											
Experiment 3	a) Write a pr	ogram to perform	the following.										
			2 until it becomes l										
			high write value 45	5H on P0.									
		t a high to low pu											
				am to check the status									
		l perform the foll	0										
		witch $= 0$, send let											
Experiment 4		vitch = 1, send let		eform of 50% duty									
Experiment 4	_	1.0 using timer 1	1	cioiiii of 5076 duty									
	· ·	U		eform of 70% duty									
	_	1.0 using timer.	e i itiliz puise wav	cionin or 7070 duty									
Experiment 5			e 8051 to transfe	r letter "A" serially,									
1	continuously												
			er the message "Y	YES" serially. Do this									
	continuously	-	č	-									
	c) Program t	he 8051 to receiv	ve bytes of data se	rially and put them in									
	P1.												
Experiment 6	-	DC and DAC.											
Experiment 7		latrix Keyboard.											
Experiment 8		ED and LCD Dis											
Experiment 9	Measuremen	t of voltage and o	current.										

Experiment 10	Controlling DC motor using PWM.								
Experiment 11	Over current digital relay								
Experiment 12	Practicals on ARDUINO								
Submission									
	Total number of Experiments:11								
Additional Information									
Course Outcome	e (CO):								
After completing	this course students will able to								
1.	Write assembly as well as c programs for microcontroller								
2.	Design delays using timers in 8051								
3.	Interface ADC, DAC, LCD, LED, Keyboard, Stepper motor, DC motor								
	etc. with 8051								
4.	Differentiate between microprocessor and microcontroller								

		РО											PSO	
	a	b	c	d	e	f	g	h	i	j	k	1	m	n
CO1														
CO2														
CO3														
CO4														

Skill Level	Exp	TA	ESE										
	1	2	3	4	5	6	7	8	9	10	11		
Assembling													
Testing													
Observing													
Analysing													
Interpreting													
Designing													
Creating													
Deducing conclusions													
Total	10	10	10	10	10	10	10	10	10	10	10	50	25

	Gov	vernment Co	ollege of Engin	eering, Karad						
	Fi	nal Year B.	Tech (Electric:	al) Sem. VIII						
	EE	1708: Electr	rical Utilization	and Traction	ı					
Teaching				Examination Sch						
Lectures		3Hrs/week		CT 1	15					
Tutorials		2Hrs/week		CT 2	15					
Total Cre	dits	5		ТА	10					
				ESE	60					
				Duration of	2Hrs.3	30				
				ESE	Min.					
Course O										
1		-	ssionally to possess i	-	ed know	wledge				
	by cou	rse contents alon	g with emerging topi	cs.						
2	To dev	velop an ability to	o design a system to	meet desired needs	of an ir	ndustry				
	within	realistic constrain	nts and confirms man	nufacturability, and	sustain	ability				
3			successful career in							
Course Co		<u>*</u>			Hours	8				
Unit I	1	trial Utilization	of Electric Motors	s: Review of natu		08				
			hing of speed torque							
			on of the load & calcu							
			tion, Control devic							
	buttons, limit switches, float switches, pressure switches, thermostats,									
			ntactor relays & sole							
			devices, application							
			anes, Lifts, Excavato	rs, Marine drives p	umps,					
Unit II		rators & air cond		astrolygic Applicat	ionof	06				
Unit II			: Faradays laws of el roplating, Anodizing			00				
			umulators & cell, T							
			lischarging, recent tr							
	batteri									
Unit III			ement of good illumi	nations, Classificati	ion of	06				
		1	es, Factor to be consid	· · · · · · · · · · · · · · · · · · ·						
	& out	door lighting sch	neme, Design proceed	lure for factory lig	hting,					
		ighting & street l								
Unit IV			dvantages of electr			08				
		0. 0	ing element in resistar	-						
			naces, Induction furn							
			Electric arc welding							
		welding.	iques like Ultrasonic	a Lasti welding,	under					
Unit V		•	fferent systems of tr	action current colle	ecting	06				
			aphs, advantages &		0	00				
	-	••••••	speed-time curve for	-						
	adhesi		pefficient of adhe		nergy					
		•	pply arrangements.	· 1	0.5					
Unit VI			Control: Desirable	characteristics of tra	action	06				
			s for traction, Contro		-					
	Shunt	transition, Bridg	ge transition, Regene	rative braking, Stu	dy of					

	performance, operation & metering system, D.C. & A. C. transition,
	introduction to modern traction systems.
List of T	utorials
	Two-tutorials based on each unit pertaining to practical / field applications.
Course (Dutcomes
After co	mpleting this course student will be able to
1	realize broad education necessary to understand the impact of electrical energy
	and its utilization in practical field, design solutions in a global and economical
	context.
2	make use of data tables & specification of various devices, appliances for
	design and applications in practical framework.
3	understand various industrial systems, its control and design.
Text Boo	oks
1	"Utilization of Electric Power & Electric Traction", J. B. Gupta, S. K. Kataria
	& Sons
Reference	ces
1	"Utilization of Electrical Engineering", O. E. Taylor, Longman
2	"Electrical Power", S. L. Uppal, Khanna Book Publication
3	"Art & Science of Utilization of Electrical Engineering", H. P. Partab,
	Dhanpat Rai Publications

	PO1	PO	PSO	PSO										
		2	3	4	5	6	7	8	9	10	11	12	1	2
CO1													\checkmark	
CO2														
CO3														
A	D 44													

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	10
Understand	3	3	2	10
Apply	3	3	2	10
Analyze	3	3	2	10
Evaluate	3	3	2	10
Total	15	15	10	50

	Governme	nt College of	Engineering, l	Karad
	Final Yea	r B. Tech. (E	lectrical) Sem	. VII
		EE 1709: S	eminar	
Seminar	Scheme		Examination Sch	eme
Practica	l 1Hrs./week		СА	25
Total	1		Total	25
Credits				
Course (Objectives			
<u> </u>	•	now the state of the	art in the relevant of	subjects of Electrical
1.	engineering.	low the state of the	art in the relevant s	subjects of Electrical
2.		come familiar with	the experimental n	procedure to validate
2.		Electrical enginee		
3.			and present researc	h topic.
Course (<u> </u>	I	
		e students on gene	ral topic related to H	Electrical engineering.
	cted topic can be any	-	1	6 6
1.		-	erring to a peer revie	ewed journal paper
2.			nal standard and its	
3.		•	article and its refere	*
			wer engineering soc	
	electronics societ	y, Industrial electro	onic society, ISO900	01-2015 etc.
Submiss	ion			
	Following are the	requisites for final	submission of sem	inar report duly
		ive guide and head		
			tion of topic (duration	
			mulation and experi	
		-	lings of literature (D	
	-	-	ort and conference re	eady paper for
	presentation (3 w	2	of pre final year stu	idents and final
			ttee along with spira	
	report(2 weeks)	pur timentur commi	ace along with spire	a bound seminar
	(_ (_)			
Course (Outcome(CO):			
1.		v the state of the ar	t in the relevant sub	jects of Electrical
	engineering.			-
2.		ble to prepare and	present research arti	icles

PO	0	PO	PO1	PO1	PO1	PSO	PSO							
1		2	3	4	5	6	7	8	9	0	1	2	1	2

CO1			 			 		
CO2	\checkmark	 	 \checkmark	\checkmark		 		
CO3			 					

	Go	vernmen	t College of	f Engineering,	Karad
	F	Final Year	· B. Tech (I	Electrical) Sen	n. VII
	E	E 1710: Ir	ndustrial T	raining Preser	ntation
Teaching S				Examinatio	
Practical		1Hr/week		CT1	
Tutorials				CT2	
Total Cred	its	2		CA	25
				ESE	
				Total	25
Course Ob	jectiv	es			
1.	To n	nake student f	amiliar with In	dustrial Environmer	nt.
2.	To n	nake student a	ware of recent	trends and technolo	gies used in industry.
3.	To in	mprove comm	nunication.		
Course Co	ntents	•			
	Stud	lents will und	lergo four weel	ks industrial trainin	ng in industry of
	their	interest durin	ng summer vac	ation. They will pre	epare report on it
	and	make present	tation before th	eir classmates and	teachers in first
	seme	ester of final y	year of B. Tech		
Course Ou					
1.	Stud	lent will be fa	miliar with Ind	ustrial Environment	•
2.					ies used in industry
3.	Stud	lent will be	able communi	cate with their co	lleagues, superiors and
	subc	ordinates in in	dustry.		

	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO1 0	PO1 1	PO1 2	PSO 1	PSO 2
CO1								\checkmark						
CO2			\checkmark	\checkmark				\checkmark	\checkmark					\checkmark
CO3									\checkmark					

Knowledge Level	CA
Remember	5
Understand	5
Describe	5
Analyze	5
Presentation Skills	5
Total	25

Elective I

	G	overnmen	t College of Engineeri	ng Karad	
]	Final Year	B. Tech (Electrical) S	Sem. VII	
E			Voltage DC Transmis		
Teaching		Ŭ		Examination Sc	
Lectures		3 Hrs/week			15
Tutorials		1			15
Total Cred	lits	4		ТА	10
				ESE	60
				Duration of	2Hrs.30
				ESE	Min.
Course Ob	ojectiv	ves			
1.	Top	provide detail	nowledge of HVDC transmiss	ion system.	
2.	To i	ntroduce basic	concepts of control and protec	tion systems in HV	/DC
		smission syste			
3.			nts to recent trends in HVDC t	ransmission system	n.
Course Co	ntent	S			Hours
Unit I		ieral Backgro			8
			sion voltages, hierarchical leve		
			tandard rated voltage of EHV		
			HVDC transmission: Constit		
			ds of DC links, HVDC proj		
			and advantages of HVDC t	ransmission over	
Unit II			HVDC station. Characteristics:		8
	_		vristor, valve-analysis with gri	d control with no	0
			ss than 60 degrees and overla		
			ns of control, power reversal, m		
			istant current versus constant		
			control, actual control charac	•	
			angle, current and extinction		
		ver control and		C	
Unit III	Fau	lts and over-v	oltages:		6
			rations: short circuit on a recti		
			d remedies, protection of HV		
		-	rcuits, over-current protection	-	
			earing and reenergizing the line	Э.	
Unit IV			eir suppression:		6
				nonics: causes,	
		-	suppression, troubles cause	•	
			types, location, series or shu	int, sharphess of	
Unit V		ng, quality fac	or. ompensation:		6
Unit V			quirement of HVDC converte	r reactive nower	U
		-	Substation, effect of angle	-	
			reactive power requirement o		
Unit VI		lti-terminal D			6
			gurations and types of MTDC	systems, control	Ň
			0	,,	1

]	MTDC	systems,	comparison	between	MTDC	and	AC	
1	interconn	ections.						L

Course	Outcomes:
After c	ompleting this course students will be able to
1.	nalyze HVDC system.
2.	Suggest appropriate control and protection schemes for HVDC system
3.	Appraise recent trends in HVDC system
Text B	ooks:
1.	Edward Wilson Kimbark "Direct Current Transmission" Wiley Interscience
	publications
2.	K R Padiyar "HVDC power transmission systems" second edition, New Age
	International Ltd
Refere	nces:
1.	EHV -AC and HVDC Transmission Engineering & Practice : S. Rao, Khanna
	Publishers, 3rd Edition, 2012.
2.	J. Arrillaga, "H.V.D.C. Transmission", Second Edition, Institution of Electrical
	Engineers, London.
Useful	Links:
1.	http://www.nptelvideos.in/2012/11/high-voltage-dc-transmission.html

	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO1 10	PO1 11	PO1 12	PSO 1	PSO 2
CO1						0	,	0		10			$\sqrt{1}$	
CO2														
CO3														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

	G	overnment	College of Engineer	ring, Karad					
		Final Year	B. Tech (Electrical)	Sem. VII					
EF			(Flexible AC Transi		ems)				
Teaching				Examination Sc	/				
Lectures		3 Hrs./week		CT1		5			
Tutorials		1		CT2	1	5			
Total Cre	dits	4		ТА	1	0			
				ESE	6	0			
				Duration of	2Hr	s.30			
				ESE	М	lin			
Course O									
1.	To u	nderstand FAC	TS concept.						
2.			with series and shunt compen	nsation using FAC	CTS de	vices.			
3.		ntroduce the co	ncept of UPFC						
Course C						lours			
			connections, Flow of Powe	•		6			
Unit I		ling Capabili	•	•	oility				
	Considerations of a Transmission Interconnection, Relative								
	-		rollable Parameters.	G 11 D	<u>~</u> ,	6			
TT •4 TT	Brief Description and Definitions of FACTS Controllers, Benefits								
Unit II	from FACTS technology, HVDC vs. FACTS Static Shunt								
	CompensatorsSVC and STATCOM: Objectives of Shunt Compensation, Methods of6								
Unit III			Generation, Static Var Com			U			
			arison Between STATCOM						
	Syste	-		and 5 v C, Static v	a				
	~		pensators: Objectives of S	Series Compensa	tion,	8			
Unit IV			Type Series Compensators,						
	Туре	e Series Compe	nsators	-					
			Phase Angle Regulators: Obje			8			
		0 0	ators, Approaches to Thyristo		0				
Unit V		and Phase Angle Regulators, Switching Converter-Based Voltage and							
	Phas	e Angle Regula	ators						
	Unif	ied Power Flo	w Controller (UPFC) and I	Interline Power H	Flow	6			
Unit VI	Cont	troller (IPFC),	Introduction, The Unified Po	ower Flow Contro	oller,				
	The	Interline Power	Flow Controller (IPFC)						
Course O	1								
1.			tand concept of FACTS.						
2.			tand series and shunt compen						
3.		ent will unders	tand voltage regulation of tra	nsmission line.					
Text Bool	1	, 1° די גר		1000					
	Und	erstanding FAC	CTS , N.G. Hingorani IEEE P	ress, 1999					
Reference									
1.			ontrol in Electrical Systems,		-				
	Ana	ya-Lara, T. J.E.	Miller Newnes Power Engin	neering Series, Ox	ford, 2	2002			

2.	2. Flexible AC transmission systems (FACTS), Yong Hua Song IEE Press, 1999									
Useful Links										
1.	http://web.iitd.ac.in									

	PO	PO	РО	PO	PO	PO	PO	РО	PO	PO	PO	PO	PS	PS
	1	2	3	4	5	6	7	8	9	10	11	12	01	O2
CO1														\checkmark
CO2														
CO3														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

	Government	t College of Engineering, Karad					
		B. Tech (Electrical) Sem. VII					
		Digital Signal Processing(DSP)					
Teaching		Examination Sch	eme				
Lectures	3 Hrs/week	CT1	15				
Tutorials		CT2	15				
Total Cre	edits 4	ТА	10				
		ESE	60				
		Duration of	2Hrs.30				
		ESE	Min				
Course O							
1		ete-Time Signals and Systems					
2	To understand Struct	ures for Discrete Time Systems					
3	To understand Filter	Design Techniques					
Course C	ontents		Hours				
Unit I	Time Systems, LTL convolution and in Difference equation Time Signals & Systime Fourier Transfe	Is and Systems: Discrete-Time Signals, Discrete- I Systems, Properties of LTI Systems, Linear its properties, Linear Constant Coefficient, s, Frequency domain representation of Discrete- stems, Representation of sequences by discrete prm, (DTFT), Properties of discrete time Fourier elation of signals, Fourier Transform	06				
Unit II	constant-coefficient, Difference equations, Freq. response of rational system functions relationship between magnitude & phase, All pass systems, inverse systems, Minimum/Maximum phase systems,						
Unit III	Structures for Discre diagram representat equations, Basic Stru	systems with linear phase Structures for Discrete Time Systems: Block Diagram and signal flow diagram representations of Linear Constant-Coefficient. Difference equations, Basic Structures of IIR Systems, Transposed forms, Direct and cascade form Structures for FIR Systems, Effects of Co-efficient					
Unit IV	Discrete-Fourier Tra The discrete Fourier Periodic Signals, S	Quantization06Discrete-Fourier Transform: Representation of Periodic sequences: The discrete Fourier Series and its Properties, Fourier Transform of Periodic Signals, Sampling the Fourier Transform, The Discrete- Fourier Transform, Properties of DFT, Linear Convolution using DFT06					
Unit V	Fast Fourier Tran Computation of DI	sform: Computational complexity of direct FT, DIT-FFT algorithm, DIF- FFT algorithm, n DIT and DIF algorithm	08				
Unit VI		ques: Design of Discrete-Time IIR filters from Iters, Approximation by derivatives, Impulse	06				

	invariance and Bilinear Transformation methods, Design of FIR								
	filters by windowing techniques, Illustrative design examples of IIR								
	and filters								
Course O	utcomes								
1	Student will understand Discrete-Time Signals and Systems								
2	Student will understand Structures for Discrete Time Systems								
3	Student will understand various Filter Design Techniques								
Text Book	XS								
1	S. K. Mitra, Digital Signal Processing: A Computer-Based Approach,								
	McGraw-Hill								
Reference	is second se								
1	Digital Signal Processing Using MATLAB (r), V. Ingle, J. Proakis,								
	Brooks/Cole Pub. Co., 1999								
2	A Course in Digital Signal Processing, B. Porat, J. Wiley and Sons, 1996:								
3	Understanding Digital Signal Processing, R. Lyons, Prentice-Hall, 1996								
4	Digital Signal Processing: Principles, Algorithms and Applications, J.								
	Proakis, D. Manolakis, Prentice-Hall, 2006 (4-th edition)								
5	Digital Filter Design, T. W. Parks and C. S. Burras, J. Wiley & Sons, 1987								
6	The Fast Fourier Transform and its Applications, E. O. Brigham, Prentice-								
	Hall, 1988								
Useful Li	ıks								
1	www.ocw.mit.edu								
2	www.nptel.iitm.ac.in								

	PO	PS	PS											
	1	2	3	4	5	6	7	8	9	10	11	12	01	O2
CO1														
CO2														
CO3														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

	(Governmei	nt College of Enginee	ring, Karad					
		Final Yea	r B. Tech (Electrical) Sem. VII					
			E 1744: FUZZY LOG						
Teaching	Sche			Examination Sch	eme				
Lectures	~~~~	3 Hrs/week		CT1	15				
Tutorials		1		CT2 15					
Total Cre	edits	4		ТА	10				
				ESE	60				
				Duration of	2Hrs.30				
~ ~ ~ ~ ~ ~				ESE	Min				
Course Ol									
1			cept of Fuzzy logic						
2		nderstand Fuz							
3			ign of Fuzzy Controllers						
Course C			~ · · · 	. ~	Hours				
Unit I	Logi Fuzz	ic, Fuzzy Cont zy Sets, Fuzzy	finitions and Concepts, Intell rol, Fuzzy Mathematics, App y System, Classic versus Fu ple of Fuzzy Control	lications, Rule Base,					
Unit II	FuzzyMathematics: FuzzySets andMembershipFunctions,Mathematical Operations on FuzzySets, FuzzyRelations, LinguisticVariables, FuzzyRules, ApproximateReasoning								
Unit III	Fuzzy Systems : Fuzzy Rule Base, Fuzzy Inference Engine, Fuzzifier, Defuzzifier, Mathematical Representations of Fuzzy Systems, The Approximation Properties of Fuzzy Systems								
Unit IV	Desi Tabl	gn of Fuzzy e Scheme	Systems Using Input-Out e, Gradient Descent						
Unit V	Algorithm, Clusteringnit VDesign of Fuzzy Controllers: Trial and Error Approach, Control surface of a fuzzy controller, Stable Fuzzy Controllers, Optimal Fuzzy Controllers, Robust Fuzzy Controllers, Fuzzy System as Sliding Mode Control, Fuzzy Sliding Mode Control, Fuzzy Supervisory Control, Fuzzy Gain Scheduling, TSK Fuzzy Systems								
Unit VI		ct Adaptive	Control: Indirect Adaptive Fuzzy Controller, Self-organ	-					
Course O	utcor	nes							
1	Stud	lent will under	stand concept of Fuzzy logic						
2	Stud	lent will under	stand Fuzzy Systems						
3	Stud	lent will be ab	le to Design of Fuzzy Control	lers					
Text Boo			-						
1		•	uzzy Logic with Engineering	Applications, Wiley	y, Fourth				
2	L. X	. Wang, "A Co	ourse in Fuzzy Systems and C	ontrol", Prentice-Ha	ll, 1997				

3	K. M. Passino, "Fuzzy Control", Addison-Wesley, 1998
Referenc	es
1	L. Reznik, "Fuzzy Controllers", 1997.
2	M. Margaliot and G. Langholz, "Fuzzy Modeling and Control", 2000.
3	H. Ying, "Fuzzy Control & Modeling", 2000
4	K. Tanaka and H. Wang, "Fuzzy Control Systems", 2001
5	G. Chen and T. T. Pham, "Introduction to Fuzzy Sets, Fuzzy Logic, and Fuzzy
	Control Systems", 2001.
6	K. Michels et. al., "Fuzzy Control, Fundamentals, Stability and Design", 2005
Useful Li	inks
1	www.ocw.mit.edu
2	www.nptel.iitm.ac.in

	PO	PO	PO	РО	РО	РО	PO	PO	PO	PO	PO	PO	PS	PS
	1	2	3	4	5	6	7	8	9	10	11	12	01	O2
CO1														\checkmark
CO2														
CO3									\checkmark					

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

	Governmen	t College of Engineering Karad	
	Final Year	B. Tech (Electrical) Sem. VII	
		wer System Operation & Control	
Teaching So		Examination Sc	heme
Lectures	3 Hrs/week	CT1	15
Tutorials	1	CT2	15
Total Credi	ts 4	ТА	10
		ESE	60
			2Hrs.30
		ESE	Min.
Course Obj	ectives		
1.	To understand the	basics of speed governing system and the concep	t of
	control areas.		
2.	To provide knowle	edge about Hydrothermal scheduling, Unit comm	itment
	and solution techn		
3.	To understand the	need of computer control in power system.	
Course Con	tents		Hours
Unit I	Introduction- Sys	stem load variation: System load characteristics,	06
	load curves - daily	y, weekly and annual, load-duration curve, load	
		actor. Reserve requirements: Installed reserves,	
		cold reserves, hot reserves. Overview of system	
	-	orecasting, techniques of forecasting, basics of	
	power system oper		
Unit II	-	frequency control- Fundamentals of speed	06
		nism and modeling,Load sharing between two	
		nines in parallel; concept of control area, LFC	
		le-area system, Multi-area systems: Two-area	
	•	ie line with frequency bias control of two-area	
TT • / TTT		state variable model.	0.6
Unit III	-	cheduling problem- Hydrothermal scheduling	06
		n and long term-mathematical model, algorithm.	
		ming solution methodology for Hydro-thermal	
		umped hydro plant: Optimization with pumped	
	• •	uling of systems with pumped hydro plant during	
	-	algorithm. Selection of initial feasible trajectory plant- Pumped hydro plant as spinning reserve	
	unit	plant- I uniped nyuro plant as spinning reserve	
Unit IV		t and economic dispatch- Statement of Unit	08
) problem; constraints in UC: spinning reserve,	00
		traints, hydro constraints, fuel constraints and	
		UC solution methods: Priority-list methods,	
		programming approach, Incremental cost curve,	
	•	ations without loss and with loss, solution by	
		λ -iteration method. Base point and participation	
		dispatch controller added to LFC control.	
Unit V		ONTROL OF POWER SYSTEMS- Energy	06
		unctions - Monitoring, data acquisition and	
		rdware configuration – SCADA and EMS	
Unit VI	POWER SYSTE	M SECURITY: Contingency analysis , linear	06
	sensitivity factors	,AC power flow methods, contingency selection	

	,concentric relaxation ,bounding-security, constrained optimal
	power flow-Interior point algorithm-Bus incremental costs.
Cours	e Outcomes:
After	completing this course students will be able to
1.	understand the basics of speed governing system and the concept of control
	areas.
2.	provide knowledge about Hydrothermal scheduling, Unit commitment and
	solution techniques.
3.	understand the need of computer control in power system.
Text E	Books:
1.	Olle. I. Elgerd, "Electric Energy Systems Theory - An Introduction", Tata
	McGraw Hill Publishing Company Ltd, New Delhi, Second Edition, 2003.
2.	D.P. Kothari and I.J. Nagrath, "Modern Power System Analysis", Third Edition,
	Tata McGraw Hill Publishing Company Limited, New Delhi, 2003.
Refere	ences:
1.	.L.L. Grigsby, "The Electric Power Engineering, Hand Book", CRC Press & IEEE
	Press, 2001.
2.	Allen.J.Wood and Bruce F.Wollenberg, "Power Generation, Operation and
	Control", John Wiley & Sons, Inc., 2003
3.	P. Kundur, Power System Stability & Control", McGraw Hill Publications, USA,
	1994.
Usefu	Links:
1.	www.nptel.com
	· · ·

	P O 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO1 0	PO1 1	PO1 2	PSO 1	PSO 2
CO1														
CO2														
CO3														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

	Government College of	Engineering, Kara	d
	Final Year B. Tech. (E	lectrical) Sem. VIII	
	EE 1807 / EE 1808: Proj	ect / Industry Proje	ect
Seminar So		Examination Scheme	
Practical	Project 10 Hrs./week	СА	100
Total	Industry Project 25 Hrs./week	ESE	200
Credits	Project 12	Total	300
	Industry Project 19		
Course Ob	jectives: Students will be able to		
Course Co	 attributes like critical thinking, creatives skills in students. The aim is also to making product from idea. Not most together. One supervisor from the depeatch. The steps involved for completion of a sight visits; interaction with content of the steps involved for product, processes, knowledge Fabrication of product, development, implementation 5. Presentation of project 	hake students aware with the re than five students may can partment shall be assigned project includes, but not list we idea through literature a community or industry, socio methods and systems using lopment of software, meas	nd communication e process involved arry out the project as guide to project mited to: and market survey; b-economic survey g multidisciplinary surement methods
Project in Academic mode	 Conceptualization of project them Learning state-of-the-art related /survey/visits/interactions (2 week) Designing of project theme and set Procurement of components (2 week) Assembly and Fabrication of proj Testing and modifications (2 week) Report writing, and conference ref Presenting project in front of depart 	to project idea through ks) election of components (2 eeks) ject work (2 weeks) ks) eady paper based on project	literature review weeks)
Project in Industry mode	The scope, objectives and time fra concerned internal guide and ind requirements of the institute. The candidate pursuing industry proje it to internal guide after every fortnig	ustry expert in tune wi	th the academic
Course Ou	tcome (CO): students will be able to		
1.	understand community needs		
2.	covert idea into product		
3.	work in group		
4.	communicate effectively.		

	РО	РО	PO	Р	РО	РО	РО	Р	PO	PO	PO	PO	PSO	PSO
	1	2	3	0	5	6	7	0	9	10	11	12	1	2
				4				8						
CO1														
CO2														
CO3														
CO4														

		Governme	ent College o	of Engineerin	ig Karad		
			U	Electrical) Se	U		
	EE 18				ctrical Machin	nes	
Teaching					Examination Scl		
Lectures	Scheme	3 Hrs/week			CT1	15	
Tutorials		2			CT2	15	
Total Cre		5			TA	10	
		-			ESE	60	
					Duration of ESE	2Hrs.30	Min.
Course O	bjectives	5				1	
1.	To unde	erstand concept	of Computer aid	led Design of Elec	ctrical Machines		
2.			ncepts in Machir				
3.			of DC Motor and				
		rse Contents				Ho	urs
Unit I					luction; Computer		08
					be fed into the pro		
					imits; Output data		
	-			• •	cameters for optim		
					xplanation of lowe	st cost	
			g/KVA"; Flowch			-	
Unit II					cable constraints N		06
					ter execution of pro		
					cal machine; Selec		
			anation of lowe	st cost and sign	ificance of "Kg/l	KVA";	
Unit III	Flowcha		E DESICN. Inter	duction Specific	ation. Output agaf	Ficianti	06
Unit III					ation; Output coeff Conducting Ma		00
				erials; Magnetic ci			
Unit IV					g and Cooling; Mo	des of	08
Unit I v		1		- · ·	; Ventilation sche		00
					es; Quantity of c		
					re; Steps to get o		
	design	., ייזרי אין אין אין אין אין אין אין אין אין אי			, 200ps 10 800 s	Pullin	
Unit V	Ŭ	JTER AIDED I	DESIGN OF DC	MACHINES: Intr	oduction; Flowcha	rts and	06
					. 2D FEM open		
			chine part design		1		
Unit VI	COMPU	JTER AIDED	DESIGN OF TR	ANSFORMERS:	Introduction; Flow	vcharts	06
	and pro	grams for com	puter aided desi	gn of transformer	rs. 2D FEM open	source	
	software	e-based transfor	rmer part design				
Course O	utcomes						
			dents will be abl				
1.		•		Design of Electrica	al Machines		
2.			pts in Machine D				
3.		and design of D	C Motor and Tra	insformer			
Text Boo							
1		shnu Murthy, C	Computer aided d	esign of electrical	machines - B S Pu	blication	IS
Reference	1			· · · ·			
1	A.K. Sa	whney,, A cour	se in Electrical n	nachine Design, D	hanpat Rai & Co.		

2	Maurya, Jallan, Shukla, Computer aided design of electrical machines –Kataria publication
Useful Li	nks:
1	http://nptel.iitm.ac.in/courses/

	PO	PO	Р	Р	PO	PO	PO	PO	PO	PO1	PO1	PO1	PSO	PSO2
	1	2	0	0	5	6	7	8	9	10	11	12	1	
			3	4										
CO1		\checkmark										$$	\checkmark	
CO2														
CO3														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

	Governi	nent College	of Enginee	ring, Ka	rad	
		ear B. Tech.				
EE 180		ter Aided De	· · · · · · · · · · · · · · · · · · ·			Lab
Laboratory Sch	eme		0		Examinatio	n Scheme
Practical	4Hrs./week				CA	50
Total Credits	2				ESE	50
					Total	100
Course Objectiv						
1.		lents familiar with				
2.		lents familiar with	n Computer aide	ed design of	Electrical ma	chines.
Course Content						
Experiment 1	transformer	ow chart and co with given specific	cations and con	-	-	
Experiment 2	Prepare a flo	ay be a better choi w chart and comp iven specification	uter program fo		lesign of start	ter for a DC
Experiment 3	Prepare a flo	w chart and comp tor with given spe	outer program f	or optimum	design of fie	ld regulator
Experiment 4		w chart and comp pecifications and c		or optimum c	lesign of a ch	oke coil
Experiment 5		w chart and com with given specifi				
Experiment 6		ow chart and co with given specifi				
Experiment 7	be used for i	w chart and comp ndustrial applicati a better choice				
Experiment 8		ow chart and com used for a lab with				a small DC
Submission						
Additional Info						
Course Outcom						
	<u> Ч</u>	tudents will fami				
1.	-	lectrical Machine	- U			
2.	Computer ai	led design of Elec	trical machines	•		

		РО												50
	a	b	c	d	e	f	g	h	i	j	k	1	m	n
CO1														
CO2														

Skill Level	Exp	TA	ESE							
	1	2	3	4	5	6	7	8		
Assembling										
Testing										
Observing										
Analysing										
Interpreting										
Designing										
Creating										
Deducing		1								2
conclusions	N	N	N	N	N	N	N	N	N	N
Total	10	10	10	10	10	10	10	10	50	25

Elective II

	Gov	vernment C	College of Enginee	ring Karad	l				
			Tech (Electrical)						
Elective-II EE 1813: Extra High Voltage AC Transmissi									
			(EHVAC)		511155	io ii			
Teaching	Scheme			Examination	Schem	е			
Lectures	Seneme	3 Hrs/week		CT1 15					
Tutorials				CT2 15					
Total Credits		3		TA	10				
		I		ESE	60				
				Duration of	2Hrs				
				ESE	Min.				
Course O	_ v								
1.	To learn calculation of EHVAC line parameters								
2.	To learn voltage gradients and corona effects								
3.		n over-voltages	and protection			II			
Course C		ation to FIN	AC Transmission : S	tour dour d turour our	inninn	Hours			
Unit I	voltages, Engineering aspect and growth of EHVAC Transmission line, trends and preliminaries, power handling capacity and line losses, calculation of line and ground parameters, transient stability limit, and								
Unit II	 Voltage gradients of conductor and corona loss: Charge-potential relations for multi-conductor lines, surface voltage gradient on conductor, distribution of voltage gradients on sub conductors of bundle. I²R and corona loss, corona-loss formulae, charge-voltage diagram and corona loss, attenuation of traveling waves due to corona loss, Audible noise, corona pulses: their generation and properties, limits for radio 								
interface fields.Theory of the Traveling waves and standing waves : Travelling and									
Unit III	standing waves at the power frequency, differential equations and solutions for general case, standing waves and natural frequencies, open ended line: double exponential response and response to sinusoidal Excitation, line energization with trapped- charge voltage, reflection and refraction of traveling waves.								
TT	Lightning and lightning protection & Insulation Co-ordinations :								
Unit IV	Lightning strokes to lines, their mechanism, General principle of the lightning protections problems, tower footing resistance, lightning arrestors and protective characteristics, Insulation level, Voltage withstands levels of protected equipment and insulation coordination based on lightning.								
Unit V	Over-voltage in EHV system caused by switching operations : Origin of over-voltages and their types, short circuit current and circuit breaker, recovery voltage and circuit breaker, over-voltages caused by								

	interruption of low inductive and capacitive currents, ferro-resonance	
	over-voltages, calculation of switching surges- single phase	
	equivalents.	
	Power frequency voltage control and over voltages : Generalized	06
	constants, no load voltage conditions and charging current, power	
Unit VI	circle diagram and its use, cascade connection of components: shunt	
	and series compensation, sub-synchronous resonance in series-	
	capacitor compensated lines, static reactive compensating systems (
	Static VAR).	
Course (Dutcomes	
After con	npleting this course students will be able to	
1.	Calculate EHVAC line parameters	
2.	Study voltage gradients and corona effects	
3.	Find over-voltages and methods of protection	
Text Boo	bks	
1	Rakosh Das Begamudre, "Extra high voltage AC transmission engineer	ing",
	4 th edition, New Age Publication.	
Reference		
1	EHV – AC and HVDC Transmission Engineering & Practice : S. Rao, K	hanna
	Publishers, 3rd Edition, 2012.	
2	Electric Power Transmission System Engineering analysis and design: 7	Farun
	Gonen, Third Edition, CRC press.	
Useful L	inks	
1	http://nptel.iitm.ac.in/courses/	

	PO	PO	Р	Р	РО	PO	РО	PO	PO	PO1	PO1	PO1	PSO	PSO2
	1	2	0	0	5	6	7	8	9	10	11	12	1	
			3	4										
CO1		\checkmark											\checkmark	
CO2														
CO3														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

	Gov	ernment (College of Engineerin	g, Karad	
	Fin	al Year B	. Tech (Electrical) Se	em. VIII	
	Ele	ctive-II El	E 1823: Wind & Sola	r power	
Teaching	Scheme		E	Examination Scl	neme
Lectures		3 Hrs/week	(CT1	15
Tutorials				CT2	15
Total Cre	dits	3	Т	A	10
				ESE	60
				Duration of	2Hrs.30
<u>C</u>				ESE	Min
Course O 1.		ratand solar ra	liation with photo thermal & p	hoto voltajo gyst	2000
					ciiis.
2.	-	-	odeling of solar energy system	ns.	
3.	I o study	y wind energy	fundamentals.		of MW
4.			ments wind turbines technolog	$gy \approx components$	OI IVI W
-	series W		1. 1 1.0		
5. Course Co		ly modern win	d turbine control & monitorin	ng system.	II
Course C		Dadiation . N	ature of Solar Radiation, G	label Deem on	Hours
Unit I			ourly, Daily and Seasonal v		
Unit I			of Solar Radiation, Measu		
	Radiatic		of Solar Radiation, Wease	fement of 501a	1
			: Solar cells & panels, perf	formance of sola	r 07
			wer obtain from solar power.		
Unit II		-	of PV systems, performance	- -	
			applications of PV systems,		
		, power plant		C	
			of solar energy systems : F (Chart method, φ	- 06
			eling & simulation of Solar E		
Unit III			f Solar energy Systems : Li		
		•••••	tems, Time Value of Mone	y, Evaluation o	f
	1		r Energy Systems.		
			mentals : Wind Energy Basi	· 1	
			oughness, Wind Mechanics,		
			, Atmospheric Boundary Lay		•
Unit IV			ts, Analysis and Energ	-	:
Unitiv			wind measurements, Wind ource estimation, Betz's Li	•	
	Analysi	-	ource estimation, betz s El		
	-		y : Airfoil terminology, Blad	e element theory	,
	-		r performance and dynamic	•	
		-	lade), Types of loads; Source		5
Unit V			nology & Components of M		. 08
- •			bes: Vertical Axis Type, I		
		• •	stant Frequency, Variable		
		1	, Down Wind, Stall Control	1	
	-	• •	tor type, Direct Generator D		
		•	or Wind Turbine Technolog	y & Component	s
	of WTG	ſ			

	1) Gear Coupled Generator Type [Const. Speed]	
	2) Direct Coupled Generator Type [Variable Speed Variable	
	Frequency]: Multipole Synchronous / PMG Generators.	
	3) Doubly Fed Induction Generator and Power Control	
	Modern Wind Turbine Control & Monitoring System : Details	08
	of Pitch System & Control Algorithms, Protections used & Safety	
	Consideration in Wind turbines, Wind Turbine Monitoring with	
	Error codes, SCADA & Databases: Remote Monitoring and	
	Generation Reports, Operation & Maintenance for Product Life	
	Cycle, Balancing technique (Rotor & Blade), FACTS control &	
	LVRT & New trends for new Grid Codes.	
Unit VI	Concept of Wind Farms and project cycle : Project planning, Site	
	selection, Project execution, Operation and maintenance	
	Environmental concerns: Pollution free power; Noise; birds;	
	Aesthetics; Radio waves interference; Rainfall.	
	Cost Economics : Wind resource assessment and R & D costs, Fixed	
	and variable costs, Value of wind energy, Life cycle costing and cash	
	flow of wind power projects, Wind project owners/developers, Wind	
	energy market	
Course O		
After taki	ng this course the students should be able to	
1.	get the concepts of solar radiations & its systems.	
2.	understand design & modeling of solar energy systems.	
3.	recognize different techniques of Wind Turbines Technology & Com	ponents
	of MW series WTGs.	
4.	familiarize with Modern Wind Turbine Control & Monitoring System	ı.
Text Book	KS	
1.	J.A.Duffie & W.A. Beckman: Solar Engineering of Thermal Process.	
2.	Anna Mani : Wind Energy Data for India.	
3.	B.H.Khan: Non-Conventional Energy Sources.	
Reference	es	
1.	C-Wet : Wind Energy Resources Survey in India VI	
2.	S. Rangrajan : Wind Energy Resources Survey in India V Sathyajith	Mathew
	: Wind Energy Prepared by WISE: Wind Power in India (5000MW B	
	2015)	
3.	S.A.Kalogirou: Solar Energy Engineering	

	PO	PO	PO	Р	PO	PO	PO	Р	PO	PO	PO	PO	PSO	PSO
	1	2	3	0	5	6	7	0	9	10	11	12	1	2
				4				8						
CO1														
CO2														
CO3														
CO4														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

		Govern	nent College of	Engineeri	ng Karad		
		Final Y	ear B. Tech (Ele	ectrical) S	em. VIII		
			I EE 1833: Rob				
Teaching	Schem				Examination Scl	heme	
Lectures		3 Hrs/week			CT1	15	
Tutorials					CT2	15	
Total Cre	dits	3			ТА	10	
					ESE	60	
					Duration of ESE	2Hrs.30	Min.
Course O	bjectiv	es					
1.	To un	derstand Autor	mation and Robotics				
2.	To un	derstand Kiner	matics of Robot				
3.	To un	derstand Dyna	mics of Robotic Manip	oulators			
		Course Conte					Iours
Unit I			botics, Historical Deve				06
			omy, Complete Classif				
			, Basic Robot Config				
			st & Gripper Subasser				
	-		oops of Robotic Sys		ent Types of Con	trollers	
			al, Differential, PID co		~ 1 \ 1		
Unit II			obot Manipulator:				06
			ctors& Matrices, Direc				
			roblem, Co-ordinate ar				
			Inverse Transforma				
			formations, Robotic Merric Network, Robotic Network, Roboti				
			Displacement Matrice				
	1 4	L	Robotic Manipulation.	s for Standard	i Configurations, J	acoulaii	
Unit III			ootic Manipulators: I	ntroduction	Preliminary Defi	nitions	06
			ic Coordinates, Jacobi				
			grangian Equations of 1				
			deling of Robotic Mar				
		•	otential Energy V of R	-	•		
	-		with Distributed Mass	,			
Unit IV			ision: Various Sensors	and their Clas	ssification, Use of	Sensors	06
		U	System in Robotics,		· · · · · · · · · · · · · · · · · · ·		
	Sensi	ng, Digitizing	, Image Processing and	d Analysis an	d Application of M	<i>lachine</i>	
	Visio	n System, Rob	otic Assembly Sensors	s and Intellige	ent Sensors.		
			tions: Objectives, A				
			lustry, Task Program	-	_		
			Robots, Future Applica				
Unit V			gies in Automation:				06
			iscrete-Manufacturing	Industries, Co	ontinuous Versus I	Discrete	
¥7 •- ***			Process and its Forms.	1		<u>a</u>	0.5
Unit VI	1 1		dustrial Control: Intro			-	06
		-	Automation Systems:				
		•	RTU. Distributed Cor	•	-	ements,	
Conver			ome popular Distribute	a Control Sys	stems.		
Course O			44 donto				
Aller com	pieting	g unis course s	tudents will be able to	J			

 To explain the basic principles of Robotic technologic programming of Robots Design an industrial robot which can meet kinematics and canalytical approaches To describe the concept of Robot kinematics and canalytical approaches To discuss and apply the concepts of dynamics for To choose the appropriate Sensor and Machine visting To identify potential areas for automation and just To identify suitable major control components requiing To identify suitable automation hardware for the gamma distribution of the gamma distribution distri	c and dynamic constraints.
 2 Design an industrial robot which can meet kinema 3 To describe the concept of Robot kinematics and oranalytical approaches 4 To discuss and apply the concepts of dynamics for 5 To choose the appropriate Sensor and Machine vis 6 To identify potential areas for automation and just 7 To select suitable major control components requi 8 To identify suitable automation hardware for the g Text Books 1. Robotics, control vision and intelligence-Fu, Lee an 2nd edition, 2007. 2 Introduction to Robotics- John J. Craig, Addison W 	
 3 To describe the concept of Robot kinematics and oranalytical approaches 4 To discuss and apply the concepts of dynamics for 5 To choose the appropriate Sensor and Machine vis 6 To identify potential areas for automation and just 7 To select suitable major control components requi 8 To identify suitable automation hardware for the g Text Books 1. Robotics, control vision and intelligence-Fu, Lee an 2nd edition, 2007. 2 Introduction to Robotics- John J. Craig, Addison W 	
 4 To discuss and apply the concepts of dynamics for 5 To choose the appropriate Sensor and Machine vis 6 To identify potential areas for automation and just 7 To select suitable major control components requi 8 To identify suitable automation hardware for the g Text Books 1. Robotics, control vision and intelligence-Fu, Lee an 2nd edition, 2007. 2 Introduction to Robotics- John J. Craig, Addison W References 	
 5 To choose the appropriate Sensor and Machine vis 6 To identify potential areas for automation and just 7 To select suitable major control components requi 8 To identify suitable automation hardware for the g Text Books 1. Robotics, control vision and intelligence-Fu, Lee an 2nd edition, 2007. 2 Introduction to Robotics- John J. Craig, Addison W References 	
 6 To identify potential areas for automation and just 7 To select suitable major control components requi 8 To identify suitable automation hardware for the g Text Books 1. Robotics, control vision and intelligence-Fu, Lee an 2nd edition, 2007. 2 Introduction to Robotics- John J. Craig, Addison W References 	typical Pick and Place robot.
 7 To select suitable major control components requi 8 To identify suitable automation hardware for the g Text Books 1. Robotics, control vision and intelligence-Fu, Lee an 2nd edition, 2007. 2 Introduction to Robotics- John J. Craig, Addison W References 	on system for a given application.
 8 To identify suitable automation hardware for the g Text Books 1. Robotics, control vision and intelligence-Fu, Lee an 2nd edition, 2007. 2 Introduction to Robotics- John J. Craig, Addison W References 	y need for automation
Text Books 1. Robotics, control vision and intelligence-Fu, Lee an 2nd edition, 2007. 2 Introduction to Robotics- John J. Craig, Addison W References	d to automate a process or an activity
 Robotics, control vision and intelligence-Fu, Lee an 2nd edition, 2007. Introduction to Robotics- John J. Craig, Addison W References 	en application.
 Robotics, control vision and intelligence-Fu, Lee an 2nd edition, 2007. Introduction to Robotics- John J. Craig, Addison W References 	
2nd edition, 2007. 2 Introduction to Robotics- John J. Craig, Addison W References	
2 Introduction to Robotics- John J. Craig, Addison W References	Gonzalez. McGraw Hill International,
References	
	sley Publishing, 3rd edition, 2010.
1. Automation, Production Systems and Computer Inter	
	rated Manufacturing M. P. Groover, Pearson
Education.5th edition, 2009.	
Useful Links	

	PO	PO	PO	PO	PO	PO	Р	PO	PO	PO	PO	PO	PSO	PSO
	1	2	3	4	5	6	O7	8	9	10	11	12	1	2
CO1													\checkmark	
CO2														
CO3														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

	G	overnmen	College of Eng	ineering Karao	d				
	F	inal Year	B. Tech (Electri	ical) Sem. VIII					
			EE 1843: Sliding	/					
Teaching				Examination		•			
Lectures		3 Hrs/week		CT1	15				
Tutorials				CT2	15				
Total Cree	dits	3		ТА	10				
		I		ESE	60				
				Duration of	2Hrs	.30			
				ESE	Min.				
Course Ob	, v								
1.		<u> </u>	yze sliding mode cont		ystems				
2.			rs for state and uncert	•					
3.			yze discrete sliding m	ode controller.					
Course Co						Hours			
Unit I	Notic	on of variable s	tructure systems and	sliding mode control.		06			
Unit II	-	gn continuous attering	sliding mode control, o	chattering issue, Alle	viation	08			
Unit III	Integ estim	-	ode Control. Sliding	Mode Observer fo	r state	06			
Unit IV	1	Discrete sliding mode control, uncertainty estimation using sliding mode							
Unit V	Discr	ete output fee	lback SMC using mul	tirate sampling		06			
Unit VI		duction to high ing algorithms	er order sliding mode	e control, twisting and	l super	06			
Course Ou		<u> </u>							
After com	pleting	g this course s	tudents will be able t	to					
1.	Desig	gn and analyze	sliding mode controll	ler for uncertain syste	ems				
2.	Desig	gn estimators f	or state and uncertaint	ty estimations.					
3.	Desig	gn and analyze	discrete sliding mode	e controller.					
Text Book									
1.			vards," Sliding Mode		Applicatio	ons"			
2.		in, Vadim ,Th	eory of Sliding Modes	, Springer					
Reference	1								
1.	1		and S. Janardhanan , '	•	0				
			t Feedback Approach ²		in Contr	ol and			
			es, Vol. 323, Springer						
2.	1		istopher Edwards, Le	-	Levant "S	Sliding			
			Observation "Birkhaus						
3.			yopadhyay and P.S. G			trol for			
		free Motion u	sing Sliding modes",	Lambert Publications	s 2012				
Useful Lin									
<u> </u>	www.n	ptel.iitm.ac.in							

	PO	PO	PO	PO	PO	PO	Р	PO	PO	PO	PO	PO	PSO	PSO
	1	2	3	4	5	6	O7	8	9	10	11	12	1	2
CO1														
CO2									\checkmark					
CO3														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

	Government	College of Engineer	ing, Karad	
	Final Year	B. Tech (Electrical)	Sem. VIII	
]		1853 Special Electric		5
Teaching S			Examination S	
Lectures	3 Hrs/week		CT1	15
Tutorials			CT2	15
Total Cred	its 3		ТА	10
			ESE	60
			Duration of	2Hrs.30
			ESE	Min.
Course Ob				
1.	To understand con	ncept of special purpose m	achines and the	ir industrial
	applications			
2.		d solid foundation in Elect		
		nd conceptual understandin	g of analytical	methods in
	special electrical M			
3.		ware of protective system wi	th industry orien	
Course Co	1		1	Hours
		tures of Synchronous Re		
TT *4 T		dial flux motors, Operating p		
Unit I	Performance chara	, Voltage & Torque equation	s, Phasor diagran	n,
			ainla af an aratia	n. 06
		ures of Stepper Motors,prir e motor, Hybrid motor, sin		
Unit II		Forque equations, Modes	•	
Unit II	0 /	ve circuits, Microprocessor		
		o control, concept of lead ang	11	
		tures of Switched Reluctant		06
		RM, principle of operation, T		
Unit III		mance prediction, Analytica		
		controllers, Methods of roto		
		on, characteristics & closed l		
		t brushless dc motors, P		et 08
		sis loop, Magnetic characte	U	
Unit IV	coefficient, princi	ple of operation, Types,	Magnetic circu	it
	analysis, EMF & T	orque equations,Commutatio	n, power converte	er
		trollers, Motor characteristics		
	-	et synchronous motors(PM	· • •	
	_ _ ·	& Torque equations,		
Unit V		ctance, sine wave motor	-	
		liagram, Torque/speed char	acteristics, powe	er
		ter volt ampere requirement.	1	
TI		cations: Synchronous Re		·
Unit VI		witched Reluctance Motor, I	-	et
Correct		s, Permanent magnet synchro	onous motors.	
Course Out		hudanta will be able to		
		tudents will be able to		
1.		ts of special electrical machin		
2.		of special electrical machine		•
3.	understand applica	tions of special electrical mag	cnines.	

Text Books	
1.	K.Venkataratnam, 'Special Electrical Machines', Universities Press (India)
	Private Limited, 2008
2.	T.J.E. Miller, 'Brushless Permanent Magnet and Reluctance Motor Drives',
	Clarendon Press,Oxford, 1989.
3.	T. Kenjo, 'Stepping Motors and Their Microprocessor Controls', Clarendon
_	Press London, 1984.
References	
1.	R.Krishnan, 'Switched Reluctance Motor Drives – Modeling, Simulation,
	Analysis, Design and Application', CRC Press, New York, 2001.
2.	P.P. Aearnley, 'Stepping Motors – A Guide to Motor Theory and Practice',
	Peter PerengrinusLondon, 1982.
3.	T. Kenjo and S. Nagamori, 'Permanent Magnet and Brushless DC Motors',
	Clarendon Press,
	London, 1988.
4.	E.G. Janardanan, 'Special electrical machines', PHI learning Private Limited,
	Delhi, 2014.
	Permanent Magnet Synchronous & Brushless DC Motor drives, R.Krishnan,
	CRC Press.
Useful Link	KS
1.	www.ocw.mit.edu
2.	www.nptel.iitm.ac.in (Video courses on Special Electrical Machines.)

8														
	PO	PSO	PSO											
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1														
CO2														
CO3														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

·			Elective III					
			ollege of Engineer	U				
	Fin	al Year B.	Tech (Electrical)	Sem. VIII				
	Elective	e-III EE 18	14: Restructured	Power System				
Teachin	g Scheme	-		Examination Sche	me			
Lectures		3 Hrs/week			15			
Tutoria				_	15			
Total C	redits	3			10			
					<u>60</u>			
					2Hrs.30			
Course	Obiostivos			ESE	Min.			
1.	Objectives	ate about variou	s power sectors in India					
2.			es between the conventio	nal power system of	peration			
<i>~</i> •	-		er system with techno-co	1 1				
3.			fundamental concepts of		nent			
Course	Contents		·	2 2	Hours			
			lia: Introduction to var		06			
			ich as CEA, Planning Co					
T T •/ T	PFC, Ministry of Power, state and central governments, R							
Unit I	Unit I utilities and their roles. Critical issues / challenges before the Indian power sector, Salient features of Electricity act 2003, Various							
	national policies and guidelines under this act.							
			Economics : Introduc	tion Reasons for	08			
			gulation of power ind					
			ved in deregulation, C					
Unit II			arket equilibrium, Short					
			of production, Market					
			nts, Comparison of vari					
			her commodities, Market		0(
			gestion management estion management meth		06			
Unit III	ATC,	Non-market	methods, Market	methods, Nodal				
0 0			and Intra zonal conge	,				
		-	management, Capacity al	-				
	Locati		al prices: Mathemat		06			
Unit IV			pricing, Lossless DCOP					
			pensated DCOPF model f	or LMP calculation,				
		F model for LN		process Treatment	06			
Unit V			on rights: FTR issuance econdary trading of FTR	-	00			
Unit v			ower, FTR and mer					
	investr	-						
Unit VI			anagement and pricin	g of transmission	08			
	netwo	rk : Introduction	on of ancillary services,	Types of Ancillary				
			n of Ancillary services					
			vices, Voltage control a					
			k start capability servi					
	ancilla	iy service, Co-	optimization of energy a	nu reserve services,				

	International comparison, Transmission pricing, Principles								
	,Classification ,Rolled in transmission pricing methods ,Marginal								
	transmission pricing paradigm ,Composite pricing paradigm ,								
	Merits and demerits of different paradigm.								
Course Outcomes									
After comp	After completing this course students will be able to								
1.	Understand various power sectors in India								
2.	Understand the restructuring of power industry and market models.								
3.	Analyze the concepts of locational marginal pricing and financial								
	transmission rights.								
Text Books	Text Books								
	Sally Hunt," Making competition work in electricity", John Willey and Sons								
	Inc. 2002								
References									
1.	Steven Stoft," Power system economics: designing markets for electricity",								
	John Wiley & Sons, 2002.								
2.	Mohammad Shahidehpour, Muwaffaq Alomoush, Marcel Dekker,								
	"Restructured electrical power systems: operation, trading and volatility"								
	Pub., 2001								
3.	Kankar Bhattacharya, Jaap E. Daadler, Math H.J. Boolen," Operation of								
	restructured power systems", Kluwer Academic Pub., 2001.								
Useful Link	XS								
	www.nptel.com								

	PO	P	PO	PO	PO	PO	PO	P	PO	PO	PO	PO	PSO	PSO
		0 2	3	4	5	6	7	0 8	9	10	11	12	1	2
CO1														
CO2		\checkmark												
CO3	\checkmark													

Knowledge Level	CT1	CT2	TA	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

		Govern	ment College of Eng	ineerin	g, Karad		
		Final	Year B. Tech (Electr	rical) Se	em.VIII		
		Elective-	III EE 1824: Power F	Plant Ei	ngineering		
Teaching	Schem				Examination Sche	me	
Lectures		3 Hrs/week		(CT1	15	
Tutorials				(CT2	15	
Total Cre	edits	3			ТА	10	
					ESE	60	
]	Duration of ESE	2Hrs.30	0Min.
Course O							
1.	To und one of		knowledge of different types of	of Power P	lants, site selection	criteria c	ofeac
2.	Under	standing of Th	ermal Power Plant Operation	n, turbine g	governing, differen	t types o	of hig
	pressu	re boilers etc.					
3.	To stu	dy of different	types of Nuclear power plants	s including	Pressurized water r	eactor, E	Boilin
			oled reactor, liquid metal fast				
4.	Unders	standing of Po	ower Plant Economics, Energ	gy Storage	including compres	ssed air e	energ
	and pumped hydro etc.						
		1		1 0			
5.	Under	*	ergy audit, environmental and	d safety as	pects of power plan		
Unit I	.	Course Cont	rents arces and development of pov	• • •			Iours 06
TT •4 TT	Power Selecti	position in In on and relativ	e, Structure of IEGC, Operati dia and Maharashtra. Power F e merits of steam, Gas, Diesel	Plants Intro l, Hydro P	oduction, Factors at ower Plants.	ffecting	0.0
Unit II	plant, pressu efficie Power variabl	of steam pow re boilers and ncy, regenerat plant: Intro- le on thermal of	er plant: Introduction, gener er plant, con treatment), nece importance of water purity, ef ion, reheating, Cogeneration p duction, general layout of ga efficiency, regeneration, rehea s turbine plant.	essity of f ffect of ope power Plar as power	feed water treatment erating variable on the start Gas turbine plant, effect of op	nt, high thermal perating	06
Unit III	Nuclea coolan Diesel	ar power plan ts, control rod Power Plant:	it: Elements of nuclear power, classification of nuclear pow Diesel engine performance an	ver plants,	waste disposal.		06
Unit IV	application, selection of engine sizeHydroelectric power plant: Hydroelectric Power Plant: site selection, classification of HPP, and their field of use, capacity calculation for hydro power, dam, head water control, penstock, water turbines, specific speeds, governors, hydroelectric plant auxiliaries, plant layout, automatic and pumped storage, project cost of hydroelectric plant. Advantages of hydro power plant.						
Unit V	Enviro Consti effect o matter	onmental asp tutes of the atr on human heal , oxides of sulp	Dects in power station : Er nosphere, Different pollutants th, environmental control of d bhur (Pre and Post Treatments) ct, Thermal Pollution of Wate	s due to the lifferent po) oxides of	ermal power plant a ollutants such as par Nitrogen ,Global w	nd their ticulate	06
Unit VI		•	and energy audit and energy and energy and operating cost, Selection		0		08

	of generation equipment, Performance and Operation Characteristics of power plants						
	and Tariff methods. Energy Audit and Energy Marketing: Selling and marketing in						
	India, Creating supply chain in India, Successfully working with business and virtual						
	teams in India, Navigating the financial, legal and accounting environment, Human						
	Resources issues, India's business culture in transition. Ratings/BIS						
Course O							
After tak	ing this course the students should be able to						
1.	Select the suitability of site for a power plant.						
2.	Calculate performance of thermal power plant.						
3.	Explain working principle of different types of nuclear power plant						
4.	Calculate load factor, capacity factor, average load and peak load on a power plant.						
5.	Indicate safety aspects of power plants.						
Text Bool	KS						
1.	1. E.I.Wakil, —Power Plant Engineering, McGraw Hill Publications New Delhi						
2.	P.K.Nag, —Power Plant Engineering, McGraw Hill Publications New Delhi.						
Reference	25						
1.	Black & Veatch, Springer, Power Plant Engineering, 1996.						
2.	Thomas C.Elliott, Kao Chen and Robert C.Swanekamp, Standard Handbook of Power Plant						
	Engineering, Second Edition, McGraw-Hill, 1998.						
3.	Godfrey Boyle, Renewable energy. Open University, Oxford University Press in association with						
	the open university,2004						

mapping	<u>n 00</u>	una 1	0											
	PO	PO	PO	РО	PO	PO	РО	PO	PO	PO	PO	PO	PSO	PSO
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1														
CO2														
CO3														
CO4														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

		Governn	ent College of Engineer	ing, Karad		
			ear B. Tech (Electrical)	U		
			e-III EE 1834: Neural N			
Teaching	g Scheme			Examination Sche	me	
Lectures		3 Hrs/week		CT1	15	
Tutorial				CT2	15	
Total Cr	redits	3		ТА	10	
				ESE	60	
				Duration of ESE	2Hrs.3	0 Min
	Objective					
			ents should be able to understa		• ••	•.
			ulloch-Pitts model and the genera	lized one, distance o	r similai	nty
			basis function model, etc. ls: multilayer perceptron, distance	or similarity based	noural	
			bry and self-organizing feature ma			d
			al network decision trees, etc.	r, indial cubib fullet		-
			he delta learning rule, the back-pa	ropagation algorithm	n, self-	
		n learning, the				
		urse Contents				ours
			ural Networks: History, Artific	cial and biological	neural	06
Unit I		-	telligence and neural networks			
Unit II		ons and Neur ent neural netw	Networks: Biological neurons, ork models	Models of single ne	eurons,	06
Unit III	0	e Layer Percing rates, Perc	ptrons : Least mean square algorr	gorithm, Learning	curves,	08
			rons : The XOR problem, Ba	ck-propagation algo	orithm,	06
Unit IV			ng the back-propagation algorithm			
Unit V			ion Networks: Interpolation,	Regularisation, Le	arning	08
T T •/ T T	strateg				•.1	0.0
Unit VI			nising Maps: Self-organising m	hap, The SOM algo	orithm,	06
Course	Outcome	ing vector qua	isation			
			lents will be able to understand			
<u>1.</u>		neuron model	tents will be able to understand			
2.		neural networ	models			
3.		learning algor				
Text Bo		uigoi				
		ırada, Introduc	ion to Artificial Neural Systems, I	PWS Publishing Cor	npany, 1	995
Referen	ces		· · · · · · · · · · · · · · · · · · ·		1 2	
		kin, Neural Ne	works: A Comprehensive Foundat	tion, Macmillan Coll	lege Pub	lishing
Co	ompany, l	.994.				
			ndamentals of Artificial Neural N			95.
		-	tals of Neural Networks: Archite	ctures, Algorithms, a	and	
			International, Inc., 1994	nhuidaa I Inizzanita - D	maga 10	06
<u>4.</u> B. Useful L		y, railern Keco	gnition and Neural Networks, Can	norlage University P	Tess., 19	70
<u>0 seiui L</u> 1.		ocw.mit.edu				
2.						
2.	WWW.	nptel.iitm.ac.ii				

	PO	РО	PO	PO	PO	PSO	PSO							
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1														
CO2														
CO3										\checkmark			\checkmark	

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

		Governm	ient College of En	gineering, Karad		
		Final Y	ear B. Tech (Elect	trical) Sem.VIII		
	Elec	ctive-III E	E 1844: Electrical	Engineering Materia	ls	
Teaching	Scheme			Examination Sche	eme	
Lectures		3Hrs/week		CT1	15	
Tutorials	1			CT2	15	
Total Cro	edits	3		ТА	10	
				ESE	60	
				Duration of ESE	2Hrs.30 N	/ir
Course C	bjectives	2			21110.001	
1.			lent with different materi	als & their characteristics used	in various	
1.		cal equipment		als & then characteristics used	i ili various	
2.			erial for manufacturing el	ectrical equipment		
		urse Content			Hou	rs
				fication of material into condu		6
				tance and factors affecting it su		-
U nit I		-	-	ucting material as low resistivi		
				ations, Super conductivity mate		
				emi-conductors and their prop		6
				germanium) used in manufact		
J nit II				n-type semiconductors), Ma		
				capacitors, diodes, transistor		
	inductor		I ,	1 , ,		
	Insulati	ing Material	- General Properties	: Electrical Properties - Ve	olume 0	6
				lectric strength (breakdown vo		
				oscopicity, tensile and compresent		
				ermal Properties- Heat resis		
				ure rise. Effect of overloading		
Unit III	life of a	n electrical ap	oliance, increase in rating	with the use of insulating ma	terials	
				ctivity, Electrothermal breakdo		
				oility, chemical resistance, w		
				icture, tensile structure IS Stan		
	1			ations: Plastics- Definition		6
	classific	ation, thermos	etting materials, Thermo	plastic materials; Natural insu	lating	
Unit IV	material	s, properties a	nd their applications; Gase	eous materials – Ceramics-prop	perties	
	and app	lications.				
	Magnet	tic Materials	and Special Materia	als: Introduction, classificat	ion - 0	6
	ferroma	gnetic materia	ls, permeability, BH cur	rve, magnetic saturation, hyst	eresis	
	loop (in	cluding) coerc	ive force and residual mag	gnetism, concept of eddy current	nt and	
Unit V	hysteres	sis loss, curie t	emperature, magnetostrict	tion effect, Soft Magnetic Mat	erials,	
	Hard ma	agnetic materi	als, Hall effect and its ap	plications. Thermocouple, bin	netals,	
	leads s	soldering and	l fuses Material - tl	heir applications. Magnetiz	ation,	
	Demagr	netizations, nai	no materials			
Course C	utcomes				· · · · · · · · · · · · · · · · · · ·	
After tak	ing this c	ourse, the stu	dents should be able to			
1.	Ĕ			f materials viz. conductors, ins	sulators,	
	-		magnetic materials etc			
2.			erial for manufacturing el	ectrical equipment		

Text Books	
	A.J. Dekker "Electrical Engineering Materials", PHI, 2006. (2rd Edition)
References	
1.	SK Bhattacharya, "Electrical and Electronic Engineering Materials"1stedition Khanna Publishers, New Delhi, 2006.
2.	S.P. Seth, P.V. Gupta "A course in Electrical Engineering Materials", Dhanpat Rai& Sons.
3.	C. S. Indulkar& S. Thiruvengadam, "Electrical Engineering Materials", S. Chand & Com. Ltd, New Delhi -55
Useful Linl	ks
	www.nptel.com

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	PO	PO	PO	PO	PO	PO	PO	Р	PO	Р	P	P	PSO	PSO
	1	2	3	4	5	6	7	08	9	01	01	01	1	2
										0	1	2		
CO1														
CO2														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60

		Govern	ment College of Eng	gineering, Karad		
		Final `	Year B. Tech (Elect	rical) Sem. VIII		
	E	ective-II E	E 1854: Electrical E	stimation and Costin	ıg	
Teaching	Schem	ie		Examination Sc	heme	
Lectures		3Hrs/week		CT1	15	
Tutorials				CT2	15	
Total Cre	edits	3		ТА	10	
		1		ESE	60	
				Duration of ESI	2 2Hrs.30	Min
Course O						
1.			pt of Electrical Estimation a			
2.			tical methods in Electrical			
3.	10 m	Course Conte		th industry oriented learning.		urs
	Draw			al Installation, General requi		06
Unit I	Electr Vario	ical Installation us diagrams, pla	, Reading and Interpretation	n of Electrical Engineering I finitions related to Installation	Drawings,	
Unit II	their f		ls of Installation of service of	ection, Types of service cont connection, Estimates of und		06
Unit III	Residu lightir numbu and ra Select MCB follow	ential Installation ag and power (er of circuits, M ating of wires of ion of rating of and wiring ac	In and positioning of equip Circuits, Procedures for de- ethod of drawing single line & Cables, Load calculation main switch, distributions b cessories, Earthing of Res ng Estimate, Preparation of	al rules & guidelines for ments, Principles of circuit signing the circuits and dec e diagram, Selection of type is and selection of size of c oard, protective switchgear H idential Installation, Sequer of detailed estimates and c	design in biding the of wiring onductor, ELCB and nee to be	06
Unit IV	Differ Funda comm nature arrang ,Earth Seque	entiate betwee mental consider aercial building, ercial building, e of supply, Dec gements and po ing of the elect	n electrification of Resid rations for planning of a , Design considerations of Load calculations & select diding the size of cables, bu sitioning of switchboards, rical Installation, Selection ed to prepare estimate, Prepa	Concept of commercial In lential and commercial In an electrical Installation sy of electrical Installation sy tion of size of service conne usbar and busbar chambers, distribution boards & ma of type wire, wiring system aration of detailed estimate an	stallation, ystem for estem for ction and Mounting in switch & layout,	06
Unit V	Electr Motor and Indust cable	rification of fa wiring circuit Motor Wiring ry/Factory/wor size & conduct	ctory unit Installation : C and single line Diagram, Im Design consideration c cshop. Motor current calcu Deciding fuse rating, starte	concept of Industrial load, C portant guidelines about pow of Electrical Installation lations, Selection and rating er, distribution boards & mai of wire, cable, conduit, earth	ver wiring in small g of wire, n Switch,	06

anthing Sequence to be followed to monome estimate. Demonstring of detailed estimate	
	06
Valid Contracts, Contract documents.	
Putcomes	
ing this course the students should be able to	
Student will be able to understand concepts of Electrical Estimation and Costing.	
Student will be able to acquired knowledge of Electrical Estimation and Costing	
Student will be able to understand Electrical Estimation and Costing fundamentals and	
various test preformed on it.	
Student will be understanding applications of Electrical Estimation and Costing	
ks	
Surjit Singh,"Electrical Estimating and costing"Dhanpat Rai and company,	
New Delhi	
K.B. Raina,S.K.Bhattacharya,"Electrical Design;Estimating and costing",	
New Age International (p)Limited, New Delhi.	
B.D.Arora," Electrical wiring, Estimating and costing", R.B. Publication, New Delhi.	
S	
N. Alagappan, S. Ekambaram,"Electrical Estimating and costing",	
Tata Mc Graw Hill Publication, New Delhi.	
S.L. Uappal," Electrical wiring Estimating and costing",Khanna Publication	
nks	
www.ocw.mit.edu	
www.nptel.iitm.ac.in (Video courses on Electrical Estimation and costing)	
	ing this course the students should be able to Student will be able to understand concepts of Electrical Estimation and Costing. Student will be able to acquired knowledge of Electrical Estimation and Costing Student will be able to understand Electrical Estimation and Costing fundamentals and various test preformed on it. Student will be understanding applications of Electrical Estimation and Costing ks Surjit Singh, "Electrical Estimating and costing" Dhanpat Rai and company, New Delhi K.B. Raina, S.K.Bhattacharya, "Electrical Design; Estimating and costing", New Age International (p)Limited, New Delhi. B.D.Arora," Electrical wiring, Estimating and costing", R.B. Publication, New Delhi. s N. Alagappan, S. Ekambaram, "Electrical Estimating and costing", Tata Mc Graw Hill Publication, New Delhi. S.L. Uappal," Electrical wiring Estimating and costing", Khanna Publication mks www.ocw.mit.edu

	PO	PO11	PO1	PSO	PSO2									
	1	2	3	4	5	6	7	8	9	10		2	1	
CO1														
CO2														
CO3														
CO4														

Knowledge Level	CT1	CT2	ТА	ESE
Remember	3	3	2	12
Understand	3	3	2	12
Apply	3	3	2	12
Analyze	3	3	2	12
Evaluate	3	3	2	12
Total	15	15	10	60